

DKE Numerical Mathematics 2017

Formula Sheet

Algebraic equations

Bisection Method f is continuous on $[a, b]$, $\text{sgn}(f(a)) \neq \text{sgn}(f(b))$.

Set $c = (a + b)/2$. If $\text{sgn}(f(a)) = \text{sgn}(f(c))$, set $a = c$, else set $b = c$.

Secant method

$$p_{n+1} = p_n - \frac{p_n - p_{n-1}}{f(p_n) - f(p_{n-1})} f(p_n).$$

Newton's method $p_{n+1} = p_n - f(p_n)/f'(p_n)$.

Polynomial Interpolation

Lagrange Form Interpolating polynomial

$$p(x) = \sum_{k=0}^n y_k l_{n,k}(x) \text{ where } l_{n,k}(x) = \prod_{\substack{j=0 \\ j \neq k}}^n \left(\frac{x - x_j}{x_k - x_j} \right)$$

Divided Differences $f[x_i] = f(x_i)$; recurrence relation

$$f[x_i, \dots, x_{i+k}] = \frac{f[x_{i+1}, \dots, x_{i+k}] - f[x_i, \dots, x_{i+k-1}]}{x_{i+k} - x_i}$$

Theorem (Divided differences and derivatives) If $f^{(n)}$ is continuous on $[a, b]$ and $x_0, \dots, x_n$ are distinct points in $[a, b]$, there exists $\xi \in [a, b]$ with

$$f[x_0, \dots, x_n] = f^{(n)}(\xi)/n!$$

Nested Form Let $a_k = f[x_0, \dots, x_k]$. Then

$$p(x) = a_0 + (x - x_0)(a_1 + (x - x_1)(a_2 + \dots + (x - x_{n-2})(a_{n-1} + (x - x_{n-1})a_n)))$$

Theorem (Error of polynomial interpolation) If p is the degree- n polynomial of interpolating f at the $n+1$ distinct nodes $x_0, x_1, \dots, x_n$ in $[a, b]$, and $f^{(n+1)}$ is continuous, then for each x in $[a, b]$, there is a ξ in (a, b) for which

$$f(x) - p(x) = \frac{1}{(n+1)!} f^{(n+1)}(\xi) \prod_{i=0}^n (x - x_i)$$

If p is the interpolating polynomial of f with $n+1$ equally-spaced nodes, then

$$|f(x) - p(x)| \leq \frac{(b-a)^{n+1}}{4n^{n+1}(n+1)!} \max_{x \in [a,b]} |f^{(n+1)}(\xi)|$$

If p is the interpolating polynomial of f with $n+1$ Chebyshev nodes, then

$$|f(x) - p(x)| \leq \frac{(b-a)^{n+1}}{2^{2n+1}(n+1)!} \max_{x \in [a,b]} |f^{(n+1)}(\xi)|$$

Cubic spline interpolation

Knots Interpolate $(x_0, y_0), \dots, (x_n, y_n)$ with knots x_j . Set $h_j = x_{j+1} - x_j$.

Interpolant $s(x) = s_j(x) = a_j + b_j(x - x_j) + c_j(x - x_j)^2 + d_j(x - x_j)^3$ for $x_j \leq x < x_{j+1}$.

Coefficients

$$a_j = y_j, \quad b_j = \frac{1}{h_j}(a_{j+1} - a_j) - \frac{h_j}{3}(2c_j + c_{j+1}), \quad d_j = \frac{1}{3h_j}(c_{j+1} - c_j).$$

Knot conditions

$$h_{j-1}c_{j-1} + 2(h_{j-1} + h_j)c_j + h_jc_{j+1} = \frac{3}{h_j}(a_{j+1} - a_j) - \frac{3}{h_{j-1}}(a_j - a_{j-1}).$$

Derivatives

$$s'_j(x_j) = b_j = \frac{1}{h_j}(a_{j+1} - a_j) - \frac{h_j}{3}(2c_j + c_{j+1}); \quad s''_j(x_j) = 2c_j.$$

Natural spline $s''(x_0) = s''(x_n) = 0$, so $c_0 = c_n = 0$.

Clamped boundary $s'(x_0) = w_0$, $s'(x_n) = w_n$, so $b_0 = w_0$; $b_n = w_n$;

$$2h_0c_0 + h_0c_1 = 3\left(\frac{a_1 - a_0}{h_0} - b_0\right); \quad h_{n-1}c_{n-1} + 2h_{n-1}c_n = 3\left(b_n - \frac{a_n - a_{n-1}}{h_{n-1}}\right).$$

Not-a-knot s''' is continuous at x_1 and x_{n-1} , so

$$h_1c_0 - (h_0 + h_1)c_1 + h_0c_2 = 0; \quad h_{n-1}c_{n-2} - (h_{n-1} + h_{n-2})c_{n-1} + h_{n-2}c_n = 0.$$

Equally-spaced $c_{j-1} + 4c_j + c_{j+1} = \frac{3}{h^2}(a_{j-1} - 2a_j + a_{j+1})$;

$$2c_0 + c_1 = \frac{3}{h^2}(a_1 - a_0 - hb_0); \quad c_{n-1} + 2c_n = \frac{3}{h^2}(hb_n - a_n + a_{n-1}).$$

Differentiation

Two-point forward difference $f'(x) = (f(x+h) - f(x))/h - f''(\xi)h/2$.

Three-point centred difference $f'(x) = (f(x+h) - f(x-h))/2h - f'''(\xi)h^2/6$.

Three-point forward difference

$$f'(x) = (-f(x+2h) + 4f(x+h) - 3f(x))/2h + f'''(\xi)h^2/3.$$

Five-point centred difference

$$f'(x) = (-f(x+2h) + 8f(x+h) - 8f(x-h) + f(x-2h))/12h + f^{(5)}(\xi)h^4/30.$$

Second derivative $f''(x) = (f(x+h) - 2f(x) + f(x-h))/h^2 - f^{(4)}(\xi)h^2/12$.

Integration

Midpoint rule $M(f, P) = h \sum_{j=1}^n f(c_j)$ where $c_j = (x_{j-1} + x_j)/2 = a + (j - \frac{1}{2})h$.

$$\text{Error } I(f) - M(f, P) = (b-a)h^2 f^{(2)}(\xi)/24.$$

Trapezoid rule $T(f, P) = h(\frac{1}{2}f(x_0) + f(x_1) + \dots + f(x_{n-1}) + \frac{1}{2}f(x_n))$.

$$\text{Error } I(f) - T(f, P) = -(b-a)h^2 f^{(2)}(\xi)/12.$$

Simpson's rule

$$S(f, P) = \frac{1}{3}h(f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + \cdots + 2f(x_{n-2}) + 4f(x_{n-1}) + f(x_n)).$$

$$\text{Error } I(f) - S(f, P) = -(b-a)h^4 f^{(4)}(\xi)/180.$$

$$\begin{aligned} \text{Error estimate } |I(f) - S(f, P_4)| &\approx |S(f, P_2) - S(f, P_4)|/15 \\ &= |f(a) - 4f(\frac{3a+b}{4}) + 6f(\frac{a+b}{2}) - 4f(\frac{a+3b}{4}) + f(b)| (b-a)/180 \end{aligned}$$

$$\text{where } P_2 = (a, \frac{a+b}{2}, b), P_4 = (a, \frac{3a+b}{4}, \frac{a+b}{2}, \frac{a+3b}{4}, b).$$

$$\text{Romberg integration } \int_a^b f(x) dx \approx R_{n,n}. \text{ Let } h_k = (b-a)/2^{k-1}.$$

$$R_{k,1} = T_{2^{k-1}}; \quad R_{k,j} = R_{k,j-1} + (R_{k,j-1} - R_{k-1,j-1})/(4^{j-1} - 1).$$

$$T_1 = \frac{b-a}{2}(f(a) + f(b)); \quad T_{2^k} = \frac{1}{2}(T_{2^{k-1}} + \frac{b-a}{2^{k-1}} \sum_{i=1}^{2^{k-1}} f(a + (2i-1)h_k)).$$

Differential Equations

$$\text{Euler's method } w_{i+1} = w_i + hf(t_i, w_i). \text{ Local error } O(h^2); \text{ global error } O(h).$$

$$\text{Error } w_{i+1} - y(t_{i+1}) = \frac{1}{2}\ddot{y}(\tau_i)h^2 \text{ for some } \tau_i \text{ in } (t_i, t_{i+1}) \text{ if } w_i = y(t_i).$$

$$\text{Taylor method } \text{Local error } O(h^3).$$

$$w_{i+1} = w_i + hf(t_i, w_i) + \frac{1}{2}h^2(f_{,t}(t_i, w_i) + f_{,y}(t_i, w_i)f(t_i, w_i)).$$

$$\text{Trapezoid (modified Euler) method } \text{Local error } O(h^3).$$

$$w_{i+1} = w_i + \frac{1}{2}h(f(t_i, w_i) + f(t_{i+1}, w_i + hf(t_i, w_i))).$$

$$\text{Midpoint method } \text{Local error } O(h^3).$$

$$w_{i+1} = w_i + hf(t_i + \frac{1}{2}h, w_i + \frac{1}{2}hf(t, w_i)).$$

$$\text{Ralston's 2nd-order method } \text{Local error } O(h^3).$$

$$\begin{aligned} w_{i+1} &= w_i + \frac{1}{4}h(f(t_i, w_i) + 3f(t_i + \frac{2}{3}h, w_i + \frac{2}{3}hf(t_i, w_i))). \\ k_{i,1} &= hf(t_i, w_i); k_{i,2} = hf(t_i + \frac{2}{3}h, w_i + \frac{2}{3}k_{i,1}); w_{i+1} = w_i(t) + \frac{1}{4}(k_{i,1} + 3k_{i,2}). \end{aligned}$$

$$\text{Heun's 3rd-order method } \text{Local error } O(h^4).$$

$$\begin{aligned} k_{i,1} &= hf(t_i, w_i); k_{i,2} = hf(t_i + \frac{1}{3}h, w_i + \frac{1}{3}k_{i,1}); k_{i,3} = hf(t_i + \frac{2}{3}h, w_i + \frac{2}{3}k_{i,2}); \\ w_{i+1} &= w_i(t) + \frac{1}{4}(k_{i,1} + 3k_{i,3}). \end{aligned}$$

$$\text{Classical 4th-order Runge-Kutta method } \text{Local error } O(h^5).$$

$$\begin{aligned} k_{i,1} &= hf(t_i, w_i); k_{i,2} = hf(t_i + \frac{1}{2}h, w_i + \frac{1}{2}k_{i,1}); \\ k_{i,3} &= hf(t_i + \frac{1}{2}h, w_i + \frac{1}{2}k_{i,2}); k_{i,4} = hf(t_i + h, w_i + k_{i,3}); \\ w_{i+1} &= w_i + k_i = w_i + \frac{1}{6}(k_{i,1} + 2k_{i,2} + 2k_{i,3} + k_{i,4}). \end{aligned}$$

$$\text{2-stage Adams-Bashforth method } \text{Local error } O(h^3).$$

$$w_{i+1} = w_i + \frac{1}{2}h(3f(t_i, w_i) - f(t_{i-1}, w_{i-1})).$$

$$\text{3-stage Adams-Bashforth method } \text{Local error } O(h^4).$$

$$w_{i+1} = w_i + \frac{1}{12}h(23f(t_i, w_i) - 16f(t_{i-1}, w_{i-1}) + 5f(t_{i-2}, w_{i-2})).$$

$$\text{2-stage Adams-Moulton method } \text{Local error } O(h^4).$$

$$w_{i+1} = w_i + \frac{1}{12}h(5f(t_{i+1}, w_{i+1}) + 8f(t_i, w_i) - f(t_{i-1}, w_{i-1})).$$

$$\text{Bogacki-Shampine adaptive method } \text{Local error } O(h^4).$$

$$\begin{aligned} k_1 &= hf(t_i, w_i); k_2 = hf(t_i + \frac{1}{2}h, w_i + \frac{1}{2}k_1); k_3 = hf(t_i + \frac{3}{4}h, w_i + \frac{3}{4}k_2); \\ w_{i+1} &= w_n + \frac{2}{9}k_1 + \frac{3}{9}k_2 + \frac{4}{9}k_3; \\ k_4 &= hf(t_i + h, w_{i+1}); \hat{w}_{i+1} = w_i + \frac{7}{24}k_1 + \frac{1}{4}k_2 + \frac{1}{3}k_3 + \frac{1}{8}k_4. \end{aligned}$$

$$\text{Set } q = (\epsilon h/|w_{i+1} - \hat{w}_{i+1}|)^{1/2}. \text{ Step size estimate } qh.$$

Least-squares approximation

$$\text{Linear least squares } g(x) = ax + b \text{ fitting data } (x_1, y_1), \dots, (x_m, y_m) \text{ where}$$

$$a = (\overline{XY} - \overline{X} \cdot \overline{Y})/(\overline{X^2} - \overline{X}^2); \quad b = \overline{Y} - a\overline{X}.$$

$$\text{Nonlinear least squares } \text{If } g(x) = \sum_{k=0}^n c_k \phi_k(x) \text{ then for } j = 0, \dots, n:$$

$$\sum_{k=0}^n c_k \sum_{i=1}^m \phi_j(x_i) \phi_k(x_i) = \sum_{i=1}^m \phi_j(x_i) y_i.$$

$$\text{Continuous least squares } \text{If } g(x) = \sum_{k=0}^n c_k \phi_k(x) \text{ fits } f(x), \text{ then for } j = 0, \dots, n:$$

$$\sum_{k=0}^n c_k \int_a^b w(x) \phi_j(x) \phi_k(x) dx = \int_a^b w(x) \phi_j(x) f(x) dx.$$

$$\text{Least-squares for orthogonal functions}$$

$$c_k = \frac{\int_a^b w(x) \phi_k(x) f(x) dx}{\int_a^b w(x) \phi_k(x)^2 dx} \quad \text{if } \int_a^b w(x) \phi_j(x) \phi_k(x) dx = 0 \text{ for } j \neq k.$$

$$\text{Generating orthogonal polynomials } \phi_k(x) = (x - B_k)\phi_{k-1}(x) - C_k\phi_{k-2}(x)$$

$$\text{with } B_k = \frac{\int_a^b x w(x) (\phi_{k-1}(x))^2 dx}{\int_a^b w(x) (\phi_{k-1}(x))^2 dx}, \quad C_k = \frac{\int_a^b x w(x) \phi_{k-1}(x) \phi_{k-2}(x) dx}{\int_a^b w(x) (\phi_{k-2}(x))^2 dx}.$$

$$\text{Legendre polynomials}$$

$$P_0(x) = 1; \quad P_1(x) = x; \quad (k+1)P_{k+1}(x) = (2k+1)xP_k(x) - kP_{k-1}(x).$$

$$\int_{-1}^1 P_j(x) P_k(x) dx = 0, \quad j \neq k, \quad \int_{-1}^1 P_k^2(x) dx = \frac{k}{2k+1}; \quad c_k = (k + \frac{1}{2}) \int_{-1}^1 P_k(x) f(x) dx.$$

$$P_0(x) = 1; \quad P_1(x) = x; \quad P_2(x) = \frac{3}{2}x^2 - \frac{1}{2}; \quad P_3(x) = \frac{5}{2}x^3 - \frac{3}{2}x; \quad P_4(x) = \frac{35}{8}x^4 - \frac{15}{4}x^2 + \frac{3}{8}.$$

$$\text{Chebyshev polynomials}$$

$$T_k(x) = \cos(k \arccos(x))$$

$$T_0(x) = 1; \quad T_1(x) = x; \quad T_{k+1}(x) = 2xT_k(x) - T_{k-1}(x)$$

$$\int_{-1}^1 \frac{T_j(x) T_k(x)}{\sqrt{1-x^2}} dx = \begin{cases} 0, & j \neq k; \\ \pi/2, & j = k \neq 0; \\ \pi, & j = k = 0. \end{cases}$$

$$\text{Fourier series}$$

$$f(x) \approx \frac{a_0}{2} + \sum_{k=1}^n (a_k \cos(kx) + b_k \sin(kx));$$

$$a_k = \frac{1}{\pi} \int_{-\pi}^{\pi} \cos(kx) f(x) dx; \quad b_k = \frac{1}{\pi} \int_{-\pi}^{\pi} \sin(kx) f(x) dx.$$

$$\text{Discrete Fourier transform } \text{If } x_j = (j/m-1)\pi \text{ for } j = 0, 1, \dots, 2m-1, \text{ then}$$

$$f(x) \approx \frac{a_0}{2} + \sum_{k=1}^n (a_k \cos(kx) + b_k \sin(kx));$$

$$a_k = \frac{1}{m} \sum_{j=0}^{2m-1} f(x_j) \cos(kx_j), \quad b_k = \frac{1}{m} \sum_{j=0}^{2m-1} f(x_j) \sin(kx_j).$$